This is to certify that the reported work in the paper entitled "Tracking Control Design for Quadrotor UAV" submitted for publication in the journal Defence Science Journal is an original one and has not been submitted for publication elsewhere. I/we further certify that proper citations to the previously reported work have been given and no data/tables/figures have been quoted verbatim from the other publications without giving due acknowledgement and without permission of the author(s). The consent of all the authors of this paper has been obtained for submitting the paper to Defence Science Journal.

Sudhin

Sudhir Author 1

A. Swarup

Author 2