# STEADY FLOW OF TWO CONDUCTING INCOMPRESSIBLE AND IMMISCIBLE FLUIDS BETWEEN TWO CONDUCTING PLATES UNDER CLOSED CIRCUIT CONDITIONS

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This paper discusses the flow of two conducting, viscous, incompressible and immiscible fluids between two conducting parallel plates in presence of an applied transverse magnetic field under general electrical loading conditions. It has been shown that the flow fluxes of the two fluids, the interface velocity and the skin friction on the two plates decrease with the increase of the total current.

#### NOMENCLATURE

$B_0$		strength of the applied magnetic	field
$\boldsymbol{E_0}$		electric field in z direction	
$h_1$	_	depth of fluid 1	
$h_2$		depth of fluid 2	🔪
$h^1_1$	· <del>_</del>	thickness of plate 1	
$h^1_2$		thickness of plate 2	•
I		total current	
Jz	. —	current density in z direction	
p		pressure	
$Q_1$	- 1	flow flux of fluid 1	·
$Q_2$	,	flow flux of fluid 2	
$u_0$		interface velocity	
$u_1$	**	velocity of fluid 1	1
$u_2$	-	velocity of fluid 2	
x, y,	z —	cartesian coordinates	
$\mu_1$		viscosity of fluid 1	
$\mu_2$	, i	viscosity of fluid 2	. /
$\sigma_1$	. <del></del>	conductivity of fluid 1	
$\sigma_2$	<del></del>	conductivity of fluid 2	
$\sigma^1_1$		conductivity of plate 1	*
$\sigma^1$		conductivity of plate 2	1.

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$$au_1$$
 — stress on plate 1

$$au_2$$
 — stress on plate 2

The problem of simultaneous flow of immiscible fluids in channels may be of importance in industrial processes such as transportation of two or more fluids in the same pipe. Bird et all discussed the flow of two viscous incompressible and immiscible fluids between two parallel plates and showed that when the heights of the two fluids are equal, the velocity maximum occurs in the less viscous fluid. Kapur & Shukla2 generalised this discussion to the case of the flow of any (finite) number of immiscible fluids occupying different heights between two parallel plates and it showed that a unique velocity maximum always exists. Later on, Kapur & Shukla<sup>3</sup> again considered the unsteady flow of two immiscible fluids occupying equal heights between two parallel plates under a time dependent pressure gradient and showed that the velocity maximum can also occur in the more viscous fluid if its density is less than that of the less viscous fluid. Kapur & Shukla4 discussed the flow of two viscous, conducting, incompressible and immiscible fluids between two parallel nonconducting plates in the presence of a transverse magnetic field neglecting induced fields. They have shown that the flow fluxes of the two fluids, the skin friction at the plates and the interface velocity decrease as the strength of the magnetic field increases. The same problem has been extended by Shukla & Prasad<sup>5</sup> taking induced fields into consideration and similar results were obtained.

Here we have considered the flow of two conducting incompressible and immiscible fluids between two parallel conducting plates in the presence of a uniform transverse magnetic field under closed circuit conditions. The main aim is to discuss the effects of the magnetic field, the total current and the conductivities of the plates on the interface velocity, the flow fluxes of the two fluids and the skin friction on the two plates,

## BASIC EQUATIONS

Consider the flow of two conducting incompressible and immiscible fluids between two conducting parallel plates in the presence of a uniform transverse magnetic field under general electrical loading conditions. A constant pressure gradient is assumed to be applied to both the fluids. The physical situation of the problem is illustrated in Fig. 1.

(1)

(2)

The basic equations governing the flow are6

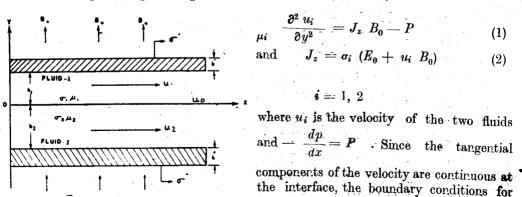


Fig. 1—Flow of two immiscible and conducting fluids.

the velocities in the two regions are as follows:

$$u_1 = 0$$
 at  $y = h_1$ 
 $u_1 = u_0$  at  $y = 0$ 
 $u_2 = 0$  at  $y = -h_2$ 
 $u_2 = u_0$  at  $y = 0$ 

where  $u_0$  is the velocity at the interface.

From (1), (2) and (3) one gets

$$u_{1} = \frac{u_{0}}{\sinh M_{1}} \sinh M_{1} \left(1 - \frac{y}{h}\right) + \left(\frac{E_{0}}{B_{0}} - \frac{P}{\sigma_{1}B_{0}^{2}}\right)$$

$$\left\{\frac{\sinh M_{1} \left(1 - \frac{y}{h}\right) + \sinh \frac{M_{1}y}{h_{1}}}{\sinh M_{1}} - 1\right\}$$
(4)

and

$$u_{2} = \frac{u_{0}}{\sinh M_{2}} \sinh M_{2} \left(1 + \frac{y}{h_{2}}\right) + \left(\frac{E_{0}}{B_{0}} - \frac{P}{\sigma_{2}B_{0}^{2}}\right)$$

$$\left\{\frac{\sinh M_{2} \left(1 + \frac{y}{h_{2}}\right) - \sinh \frac{M_{2}y}{h_{2}}}{\sinh M_{2}} - 1\right\}$$
(5)

where  $M_1^2 = \frac{\sigma_1}{\mu_1} B_0^2 h_1^2$  and  $M_2^2 = \frac{\sigma_2}{\mu_1} B_0 h_2^2$ .

It is convenient to use the following dimensionless variables for further analysis

$$\bar{u}_{1} = \frac{\mu_{1}u_{1}}{Ph_{1}^{2}} ; \quad \bar{u}_{2} = \frac{\mu_{2} u_{2}}{Ph_{2}^{2}} ; \quad \bar{u}_{0} = \frac{\mu_{1} u_{0}}{Ph_{1}^{2}}$$

$$\bar{E}_{0} = \frac{\mu_{1}E_{0}}{B_{0}Ph_{1}^{2}}; \quad \bar{y} = \frac{y}{h_{1}} ; \quad \bar{h} = \frac{h_{1}}{h_{2}}$$

$$\mu^{2} = \frac{\mu_{2}}{\mu_{1}} ; \quad \frac{\sigma_{2}}{\sigma_{1}} = \lambda^{2} = \frac{\bar{h}^{2} \mu^{2} M_{2}^{2}}{M_{1}^{2}}$$
(6)

Equations (4) and (5) then take the forms:

$$\overline{u_1} = \frac{\overline{u_0}}{\sinh M_1} \frac{\sinh M_1 (1 - \overline{y})}{\sinh M_1} + \left(\overline{E}_0 - \frac{1}{M_1^2}\right) \left\{ \frac{\sinh M_1 (1 - \overline{y}) + \sinh M_1 \overline{y}}{\sinh M_1} - 1 \right\}$$
(7) a d

$$\bar{u_2} = \frac{\mu^2 \bar{u_0} h^2 \sinh M_2 (1 + \bar{h} \bar{y})}{\sinh M_2} + \left(\mu^2 \bar{h} \bar{E}_0 - \frac{1}{M_2^2}\right) \left\{ \frac{\sinh M_2 (1 + \bar{h} \bar{y}) - \sinh M_2 \bar{h} \bar{y}}{\sinh M_2} - 1 \right\}$$
(8)

Since at the interface the shearing stress is constant

$$h^{-2} \left( \frac{\overline{\partial u_1}}{\overline{\partial u}} \right)_{y=0} = \left( \frac{\overline{\partial u_2}}{\overline{\partial u}} \right)_{y=0} \tag{9}$$

From (7), (8) and (9) one gets

$$\overline{u_0} = \frac{\frac{1}{M_1} \tanh \frac{M_1}{2} + \frac{1}{M_2 h} \tanh \frac{M_2}{2} - \overline{E_0} M_1 \left( \tanh \frac{M_1}{2} + \lambda \mu \tanh \frac{M_2}{2} \right)}{M_1 \left( \coth M_1 + \lambda \mu \coth M_2 \right)}$$
(10)

The total current I is given by

$$I = \int_{0}^{L} \left[ \sigma_{2}^{1} \int_{-(h''+h_{2})}^{-h_{2}} E_{0} dy + \sigma_{2} \int_{-h_{2}}^{0} (E_{0} + u_{2} B_{0}) dy + \sigma_{1} \int_{-(h''+h')}^{h_{1}} (E_{0} + u_{1} B_{0}) dy + \sigma_{1}^{1} \int_{-L}^{h_{1}+h'} E_{0} dy \right] dx$$

which on using (4), (5) and (6) gives

$$I = M_{1} \overline{E}_{0} \left[ \frac{\overline{h_{1}} \lambda_{1}^{2}}{\overline{h}} + \frac{\overline{h_{2}} \lambda_{1}^{2}}{\overline{h}} + \frac{2}{M_{1}} \tanh \frac{M_{1}}{2} + \frac{2\lambda \mu}{M_{1}} \tanh \frac{M_{2}}{2} \right] + \overline{u_{0}} \left[ \tanh \frac{M_{1}}{2} + \lambda \mu \tanh \frac{M_{2}}{2} \right] - \frac{1}{M_{1}} \left[ \left( \frac{2}{M_{1}} \tanh \frac{M_{1}}{2} - 1 \right) + \frac{1}{\overline{h}} \left( \frac{2}{M_{2}} \tanh \frac{M_{2}}{2} - 1 \right) \right]$$

$$(12)$$

where  $\overline{I} = \frac{I}{LPh_{1}^{2}} \sqrt{\frac{\mu_{1}}{\sigma_{1}}}$ 

$$\lambda^2_{1}=rac{\sigma^1_{1}}{\sigma_{1}}$$
 ,  $\lambda^2_{2}=rac{\sigma^1_{2}}{\sigma_{1}}$  ,  $ar{h_1}=rac{h_1^{\;1}}{h_2}$  ,  $ar{h_2}=rac{h_2^{\;1}}{h_2}$ 

which on using (10) gives  $\overline{E}_0$  as a function of I

$$M_{1} \overline{E}_{0} \left[ \frac{\overline{h_{1}} \lambda_{1}^{2}}{\overline{h}} + \frac{\overline{h_{2}} \lambda_{2}^{2}}{\overline{h}} + \frac{2}{M_{1}} \left( \tanh \frac{M_{1}}{2} + \lambda \mu \tanh \frac{M_{2}}{2} \right) - \frac{\left( \tanh \frac{M_{1}}{2} + \lambda \mu \tanh \frac{M_{2}}{2} \right)^{2}}{M_{1} \left( \coth M_{1} + \lambda \mu \coth M_{2} \right)} \right] = \overline{I} + \frac{1}{M_{1}} \left[ \left( \frac{2}{M_{1}} \tanh \frac{M_{1}}{2} - 1 \right) + \frac{1}{\overline{I}} \left( \frac{2}{M_{2}} \tanh \frac{M_{2}}{2} - 1 \right) \right]$$

$$-\left[\frac{\left(\tanh\frac{M_1}{2} + \lambda \mu \tanh\frac{M_2}{2}\right) \left(\tanh\frac{M_1}{2} + \frac{\mu}{\lambda} \tanh\frac{M_2}{2}\right)}{M_1^2 \left(\coth M_1 + \lambda \mu \cosh M_2\right)}\right]^{2\gamma}$$
(13)

This equation determines the constant  $E_0$  explicitly in terms of the total current I.

DETERMINATION OF SKIN FRICTION AND FLOW FLUX

If the skin frictions on the upper and the lower plates be  $\tau_1$  and  $\tau_2$  then, with the help of (7) and (8), one gets

$$\begin{split} \overline{\tau}_1 &= \frac{\tau_1}{Ph_1} = -\left(\frac{du_1}{d\overline{y}}\right)_{\overline{y}=1} \\ &= \frac{M_1\overline{u}_0}{\sinh M_1} - M_1\left(\overline{E}_0 - \frac{1}{M_1^2}\right) \tanh \frac{M_1}{2} \end{split} \tag{14}$$

and

If Q1 and Q2 be the corresponding flow fluxes, one also gets

$$\overline{Q}_{1} = \frac{\mu_{1} Q_{1}}{P h_{1}^{3}} = \int_{0}^{1} \overline{u}_{1} d\overline{y}$$

$$= \frac{\overline{u}_{0} \tanh \frac{M_{1}}{2}}{M_{1}} - \left(\overline{E}_{0} - \frac{1}{M_{1}^{2}}\right) \left(1 - \frac{2}{M_{1}} \tanh \frac{M_{1}}{2}\right) \quad (16)$$

and

$$\begin{split} \bar{Q}_2 &= \frac{\mu_2 \, Q_2}{P h_2^3} &= \frac{1}{\bar{h}} \int \bar{u}_2 \, d\bar{y} \\ &- \frac{1}{\bar{h}} \end{split}$$

$$&= \frac{\mu^2 \, \bar{u}_0}{M_2} \, \tanh \frac{M_2}{2} - \left( \mu^2 \, \bar{h} \, \overline{E_0} - \frac{1}{M_2^2} \right) \left( \frac{1}{\bar{h}^2} - \frac{2 \, \tanh \frac{M_2}{2}}{M_2 \, \bar{h}^2} \right) \end{split}$$

Now from equations (7), (8), (10), and (13) to (17) one can find the explicit expressions for  $u_1$ ,  $u_2$ ,  $u_0$ ,  $\tau_1$ ,  $\tau_2$ ,  $Q_1$  and  $Q_2$  in terms of I.

## Particular Case

Let us discuss the following particular case:

Consider the plates to be of the same material and of the same thickness and assume that the fluids occupy the same height between the plates. Then

$$\overline{h} = 1$$
;  $\frac{h_1^1}{h_2} = \overline{h_1} = \overline{h_2} = \frac{h_2^1}{h_2} = b$  (say)
$$\lambda_1 = \sqrt{\frac{\sigma_1^1}{\sigma_2}} = \lambda_2 = \sqrt{\frac{\sigma_2^1}{\sigma_2}} = K$$
 (say)

With the help of (10) and (12) the various expressions take the forms:

$$\frac{2}{M_{1}} + 2bK^{2} \left( \frac{\frac{1}{M_{1}} \tanh \frac{M_{1}}{2} + \frac{1}{M_{2}} \tanh \frac{M_{2}}{2}}{\tanh \frac{M_{1}}{2} + \lambda \mu \tanh \frac{M_{2}}{2}} \right) - \overline{I}$$

$$\frac{1}{M_{1}bK^{2}} \left( 1 + \frac{\coth \frac{M_{1}}{2} + \lambda \mu \coth \frac{M_{2}}{2}}{\tanh \frac{M_{1}}{2} + \lambda \mu \tanh \frac{M_{2}}{2}} \right) + \left( \coth \frac{M_{1}}{2} + \lambda \mu \coth \frac{M_{2}}{2} \right)$$
(18)

Equations (10) and (18) show that  $\overline{u_0}$  is a linear function of  $\overline{I}$  and decreases as the total current increases. This is also obvious from Fig. 2.

$$M_{1} \overline{E}_{0} \left\{ 2 bK^{2} + \frac{2}{M_{1}} \left( \tanh \frac{M_{1}}{2} + \lambda \mu \tanh \frac{M_{2}}{2} \right) - \frac{\left( \tanh \frac{M_{1}}{2} + \lambda \mu \tanh \frac{M_{2}}{2} \right)^{2}}{M_{1} \left( \coth \overline{M}_{1} + \lambda \mu \coth \overline{M}_{2} \right)} \right\}$$

$$= \overline{I} + \frac{1}{M_{1}} \left[ \frac{2}{M_{1}} \tanh \frac{M_{1}}{2} + \frac{2}{M_{2}} \tanh \frac{M_{2}}{2} - 2 \right]$$

$$- \frac{\left( \tanh \frac{M_{1}}{2} + \lambda \mu \tanh \frac{M_{2}}{2} \right) \left( \tanh \frac{M_{1}}{2} + \frac{\mu}{\lambda} \tanh \frac{M_{2}}{2} \right)}{M_{1}^{2} \left( \coth M_{1} + \lambda \mu \coth M_{2} \right)}$$

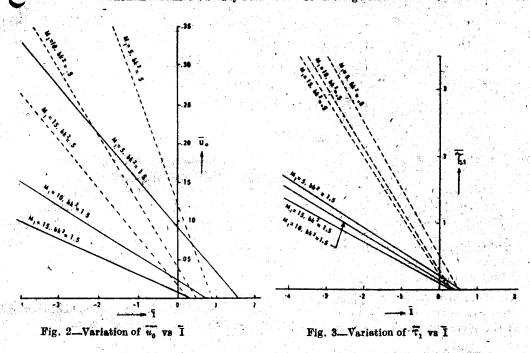
$$(19)$$

$$\overline{\tau_1} = \frac{M_1 \ \overline{u_0}}{\sinh M_1} - M_1 \left( \overline{E_0} - \frac{1}{M_1^2} \right) \tanh \frac{M_1}{2} \tag{20}$$

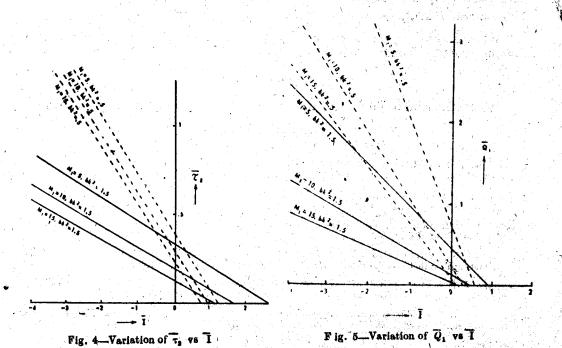
$$\overline{\tau_2} = \frac{\mu^2 M_2 u_0}{\sinh M_2} - M_2 \left( \mu^2 \bar{E}_0 - \frac{1}{M_2^2} \right) \tanh \frac{M_2}{2}$$
 (21)

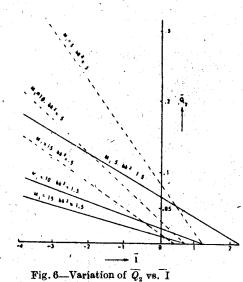
$$\bar{Q}_1 = \frac{\bar{u}_0}{M_1} \tanh \frac{M_1}{2} - \left(\bar{E}_0 - \frac{1}{M_1^2}\right) \left(1 - \frac{2}{M_1} \tanh \frac{M_1}{2}\right) \tag{22}$$

$$\bar{Q}_2 = \frac{\mu^2 u_0}{M_2} \tanh \frac{M_2}{2} - \left(\mu^2 E_0 - \frac{1}{M_2^2}\right) \left(1 - \frac{2}{M_2} \tanh \frac{M_2}{2}\right)$$
 (23)



Keeping the conductivities and the viscosities of the fluids fixed, the varieties of  $\overline{u_0}$ ,  $\overline{\tau_1}$ ,  $\overline{\tau_2}$ ,  $\overline{Q_1}$  and  $\overline{Q_2}$  versus  $\overline{I}$  are shown in Fig. 2 to 6 respectively for various values of M. The following results are obtained:





Results obtained from Fig 2: (i) the interface velocity  $\overline{u_0}$  decreases as the strength of the magnetic field increases for fixed values of  $\overline{I}$  and  $bK^2$ ; (ii) the interface velocity  $\overline{u_0}$  decreases as  $bK^2$  i.e., the conductivity or the thickness of the plates increases for fixed negative values of  $\overline{I}$  and the strength of the magnetic field.

Results obtained from Fig. 3 and  $\underline{4}$ : (i) for fixed  $bK^2$  and regative values of  $\overline{I}$ , the skin friction at the plates increases as the strength of the magnetic field increases; (ii) for fixed values of the applied magnetic field and negative values of  $\overline{I}$ , the skin friction at the plates decreases as  $bK^2$ , i.e. the conductivity or the thekness of the plates increases;

(iii) for fixed values of applied magneto field and  $bK^2$ , the skin friction at the plates decreases as the total current increases. Thus it is possible to minimise the skin friction at the plates by choosing suitable configuration of the external electric field.

Results obtained from Fig. 5 and 6: (i) for fixed  $bK^2$  and negative values of I, the flow fluxes of the fluids decrease as the strength of the magnetic field increases; (ii) for fixed values of the applied magnetic field and negative values of I, the flow fluxes of the fluids decrease as  $bK^2$ , i.e., the conductivity or the thickness of the plates increases; (iii) for fixed values of applied magnetic field and  $bK^2$ , the flow fluxes of the fluids decrease as the total current I increases.

When the total current is zero and the plates are non-conducting one gets all the results obtained by Shukla & Prasad<sup>5</sup>.

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