

ON PARTICULAR SOLUTIONS OF $\nabla^4 \phi = 0$ AND $E^4 \phi = 0$.

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ABSTRACT

The correspondence between the particular solutions of the equations $\nabla^4 \phi = 0$ and $E^4 \phi = 0$ are pointed out. The solutions obtained already by Bhatnagar¹ are compared. An elementary discussion of the operational equation $[F_1 F_2 (L_1 + L_2)] \phi = 0$ is presented. The operations E_{ν}^2 , E_{ν}^4 , H_{ν}^2 and H_{ν}^4 are introduced.

INTRODUCTION

The Laplacian operator is denoted by ∇^2 and can be identified with $\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$ in the cartesian system (rectangular).

The operator E^2 stands for $\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial \omega^2} - \frac{1}{\omega} \frac{\partial}{\partial \omega}$. Recently, some particular solutions were obtained for the equation $E^4 \phi = 0$ by Bhatnagar¹. The correspondence between the particular solution of $\nabla^4 \phi = 0$ and $E^4 \phi = 0$ was not brought forth in the paper, or atleast was not pointed out and hence some results relating the particular solutions of the biharmonic equation and $E^4 \phi = 0$ are presented here.

Considering the operator, $E^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial \omega^2} - \frac{1}{\omega} \frac{\partial}{\partial \omega}$, it can be seen that

$E^2 f(x, \omega) = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial \omega^2} - \frac{1}{\omega} \frac{\partial f}{\partial \omega}$ can be transformed into a form involving the operator ∇^2 by the simple substitution :

$$(1) \quad f = \omega F;$$

$$\frac{\partial f}{\partial \omega} = \omega \frac{\partial F}{\partial \omega} + F \quad \text{and}$$

$$\frac{\partial^2 f}{\partial \omega^2} = \omega \frac{\partial^2 F}{\partial \omega^2} + 2 \frac{\partial f}{\partial \omega} \quad \text{and hence}$$

$$(2) \quad E^2 f = \omega \left(\frac{\partial^2 F}{\partial x^2} + \frac{\partial^2 F}{\partial \omega^2} + \frac{1}{\omega} \frac{\partial F}{\partial \omega} - \frac{F}{\omega^2} \right)$$

We define ∇^2 in (x, ω, ϕ) coordinate system and express ∇^2 as

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial \omega^2} + \frac{1}{r} \frac{\partial}{\partial \omega} + \frac{1}{\omega^2} \frac{\partial^2}{\partial \phi^2} \quad \text{and}$$

$$\nabla^2 (F e^{i\phi}) = \left(\frac{\partial^2 F}{\partial x^2} + \frac{\partial^2 F}{\partial \omega^2} + \frac{1}{\omega} \frac{\partial F}{\partial \omega} - \frac{F}{\omega^2} \right) e^{i\phi}$$

where F has been assumed to be independent of ϕ .

Recalling the operation of ∇^2 in the (x, ω, ϕ) system (cylindrical polar coordinates) on functions independent of ϕ , we may write,

$$(3) \quad \nabla^2(x, \omega) = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\omega^2} + \frac{1}{\omega} \frac{\partial}{\partial \omega},$$

It is easily seen that,

$$(4) \quad \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial \omega^2} - \frac{1}{\omega} \frac{\partial}{\partial \omega} \right) (\omega F e^i) \\ = \omega \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial \omega^2} + \frac{1}{\omega} \frac{\partial}{\partial \omega} - \frac{1}{\omega^2} \frac{\partial^2}{\partial \phi^2} \right) (F e^i)$$

and hence,

$$(5) \quad E^2 f = E^2(\omega F) = \omega \left(\nabla^2(x, \omega) - 1/\omega^2 \right) F.$$

To obtain a particular solution of the equation $E^2 f = 0$, one only needs a particular solution of $\nabla^2 \phi = 0$, where ∇^2 is the Laplacian operator in (x, ω, ϕ) system and the particular solution Φ depending on " ϕ " as $\omega F e^i \Phi$; If such a solution is found, f can be written as ωF ;

[Note: The operator E^2 is independent of ϕ]

$$E^4 f = E^2(E^2 f)$$

$$\text{writing } f = \omega F e^i \Phi$$

$$E^4(\omega F e^i \Phi) = e^i \Phi E^2[E^2(\omega F)]$$

$$\text{Also, } \omega \nabla^2(F e^i \Phi) = E^2(\omega F e^i \Phi)$$

consequently

$$E^4(\omega F e^i \Phi) = E^2.E^2(\omega F e^i \Phi) \\ = E^2.\omega(\nabla^2 x, \omega - 1/\omega^2). F e^i \Phi \\ = \omega(\nabla^2 x, \omega - 1/\omega^2)^2 F e^i \Phi \\ = \omega \nabla^4 F e^i \Phi \quad \text{and hence}$$

$$\omega \nabla^4(F e^i \Phi) = E^4(f e^i \Phi) \quad [\nabla^2 \equiv \text{Three dimensional Lap'acian operator}]$$

To obtain a particular solution of $E^4 \phi = 0$, one can search for a particular solution of $\nabla^4 \Phi = 0$ of the form $\Phi = F e^i \Phi$ (F independent of ϕ) and 'convert it' to a solution of $E^4 \Phi = 0$ by multiplying F by ω .

To summarise:

consider the operators

$$E^2 \equiv \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial \omega^2} - \frac{1}{\omega} \frac{\partial}{\partial \omega} \right) (x, \omega)$$

and

$$\nabla^2 \equiv \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial \omega^2} + \frac{1}{\omega} \frac{\partial}{\partial \omega} + \frac{1}{\omega^2} \frac{\partial^2}{\partial \phi^2} \right) (x, \omega \phi)$$

Assume a solution of the form $\Phi = F(x, \omega) e^{i\phi}$ to the equation $\nabla^2 \Phi = 0$. Then, a particular solution of $E^2 \Phi = 0$ is ωF ; Also if $F(x, \omega) e^{i\phi} = \Phi$ is a solution of $\nabla^4 \Phi = 0$; $\omega F = \psi$ is a solution of $E^4 \psi = 0$.

ILLUSTRATIONS

Obviously, if Φ satisfies the equation $\nabla^2 \Phi = 0$ it is a solution of $\nabla^4 \Phi = 0$ too.

Assuming the ϕ dependence of $\Phi = F e^{i\phi}$ as that of $e^{i\phi}$ we seek the solutions of $\frac{\partial^2 F}{\partial x^2} + \frac{\partial^2 F}{\partial \omega^2} + \frac{1}{\omega} \frac{\partial F}{\partial \omega} - \frac{F}{\omega^2} = 0$

It is well known that

$$\begin{matrix} \cosh \\ \sinh \end{matrix} mx \left\{ \begin{matrix} A J_1(m\omega) + B Y_1(m\omega) \end{matrix} \right\}$$

(for any $m \neq 0$)

are among these.

Hence,

$$(7) \quad \phi = \omega \begin{matrix} \cosh \\ \sinh \end{matrix} mx \left\{ \begin{matrix} A J_1(m\omega) + B Y_1(m\omega) \end{matrix} \right\}$$

are solutions of $E^2 \Phi = 0$ and hence of $E^4 \Phi = 0$. Also,

$$7(a) \quad \phi = \omega \begin{matrix} \cos \\ \sin \end{matrix} mx \left\{ \begin{matrix} A^1 I_1(m\omega) + B^1 K_1(m\omega) \end{matrix} \right\}$$

are solutions of $E^2 \Phi = 0$ and $E^2 \Phi = 0$.

If f is such that $E^2 \Phi = f$ where f is a solution of $E^2 f = 0$, Φ will be a solution of $E^4 \Phi = 0$; Thus we generate some more particular solutions for $E^4 \Phi = 0$.

Since the general solution of

$$\frac{d^2 y}{d\omega} + \frac{1}{\omega} \frac{dy}{d\omega} + \left(m^2 - \frac{1}{\omega^2} \right) y = A J_1(m\omega) + B Y_1(m\omega) \\ = V(m\omega), \text{ say,}$$

can be expressed as,

$$(8) \quad J_1(m\omega) \left[C_1 - \int_{\alpha}^{\omega} \omega V(mx) Y_1(mx) dx \right] + Y_1(m\omega) \left[C_2 + \int_{\beta}^{\omega} \omega V(mx) J_1(mx) dx \right]$$

where C_1, C_2, α and β are arbitrary constants, some particular solutions of $E^4 \Phi = 0$ take the form as expressed by equation 2·18 in the paper by Bhatnagar¹.

Simple manipulations result in the new particular solutions given by equation 2·26 of reference 1. Since

$$\left(\frac{\partial^2}{\partial \omega^2} + \frac{1}{\omega} \frac{\partial}{\partial \omega} - \frac{1}{\omega^2} \right) (A\omega + B/\omega) \equiv 0$$

and

$$\frac{\partial^2}{\partial x^2} \left(\frac{\partial^2}{\partial x^2} \right) (a + bx + cx^2 + dx^3) = 0$$

some more solutions of $\nabla^4 \Phi = 0$ can be seen to be of the form,

$$(a + bx + cx^2 + dx^3) (A\omega + B/\omega) e^{i\theta} \text{ and hence}$$

$$(9) \quad (a + bx + cx^2 + dx^3) (A\omega^2 + B) = \Phi$$

is a solution of $E^4 \Phi = 0$.

(a, b, c, d, A and B are arbitrary constants)

[cf: equation 2·30 of reference 1]

Also from the solution of

$$\left(\frac{\partial^2}{\partial \omega^2} + \frac{1}{\omega} \frac{\partial}{\partial \omega} - \frac{1}{\omega^2} \right) f = A\omega + B/\omega,$$

it is seen that

$$(10) \quad [C_1 + (C_2 + C_3 \log \omega) \omega^2 + C_4 \omega^4] (a + bx) \text{ is a solution of } E^4 \Phi = 0. \\ \text{(equation 2·9 of reference 1).}$$

By similar arguments,

$$\omega \begin{matrix} \cos \\ \sin \end{matrix} \lambda x \begin{matrix} I_1 \\ K_1 \end{matrix} (\lambda \omega); \quad \omega \begin{matrix} \cosh \\ \sinh \end{matrix} \lambda x \begin{matrix} J_1 \\ Y_1 \end{matrix} (\lambda \omega)$$

(11) and

$$x\omega \begin{matrix} \cos \\ \sin \end{matrix} \lambda x \begin{matrix} I_1 \\ K_1 \end{matrix} (\lambda \omega); \quad x\omega \begin{matrix} \cosh \\ \sinh \end{matrix} \lambda x \begin{matrix} J_1 \\ Y_1 \end{matrix} (\lambda \omega)$$

can be proved to be particular solutions (cf: equation 2·39 reference 1)

Polar coordinates:

The correspondence, that has been proved to exist, between the solutions of $E^4 \Phi = 0$ and $\nabla^4 \Phi = 0$ is particularly useful in helping us to choose the proper particular solutions in other systems of coordinates.

Considering, for instance, spherical polar coordinates for which $\nabla^2 \mathcal{U}$ assumes the form

$$\nabla^2 \mathcal{U} = \frac{1}{r^2} \left\{ \frac{\partial}{\partial r} \left(r^2 \frac{\partial^2 \mathcal{U}}{\partial r^2} \right) + \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \mathcal{U}}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 \mathcal{U}}{\partial \phi^2} \right\},$$

it may first be pointed out that only those solutions of $\nabla^2 \mathcal{U} = 0$ or $\nabla^4 \mathcal{U} = 0$ whose dependence on ϕ is as $e^{i\phi}$ are of interest in the discussion of $E^4 \Phi = 0$.

It may be recalled that a typical solution of $\nabla^2 \Phi = 0$ which is of the form $F(r, \theta) e^{i\phi}$ is given by

$$(12) \quad F = (Ar^n + Br^{-n-1}) [CP'_n(\mu) + DQ'_n(\mu)]$$

The particular solutions of $\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \mathcal{U}}{\partial r} \right) = Ar^n + Br^{-n-1}$

will be of the form $A'r^{n+2} + B'r^{-(n-1)}$ and hence there exist particular solutions of $E^4 \Phi = 0$ which are of the form,

$$(13) \quad \left(\frac{B}{r^n} + A'r^{n+3} + \frac{B'}{r^{n-2}} + Ar^{n+1} \right) \left\{ a_1 P'_n(\mu) + b_1 Q'_n(\mu) \right\} \left(r\sqrt{1-\mu^2} \right).$$

(cf: equation 3.19, reference 1)

In the degenerate case, $n=0$, we may easily prove that the solutions will be

$$(14) \quad (B + A'r^3 + B'r^2 + Ar) (a_1 + a_2 \mu).$$

It can be shown that a solution of $\nabla^4 \Phi = 0$

can be given in the form $r^m f(\mu)$ where f is a solution of

$$\left[\frac{\partial}{\partial \mu} \left((1-\mu^2) \frac{\partial}{\partial \mu} \right) + (m-2)(m-1) - \frac{1}{1-\mu^2} \right] \left\{ \frac{\partial}{\partial \mu} \left[(1-\mu^2) \frac{\partial}{\partial \mu} \right] + m(m+1) - \frac{1}{1-\mu^2} \right\} f = 0$$

A typical solution will be given by

$$(15) \quad \left\{ \frac{\partial}{\partial \mu} \left((1-\mu^2) \frac{\partial}{\partial \mu} \right) + m(m+1) - \frac{1}{1-\mu^2} \right\} f = 0$$

which can be expressed as $A P'_m(\mu) + B Q'_m(\mu)$

Also, If

$$(16) \quad \left\{ \frac{\partial}{\partial \mu} \left((1-\mu^2) \frac{\partial}{\partial \mu} \right) + m(m+1) - \frac{1}{1-\mu^2} \right\} P(\mu) = A_1 P'_{m-2}(\mu) + B_1 Q'_{m-2}(\mu),$$

$$(17) \quad \left\{ r^{m+1} f(\mu) \sqrt{1-\mu^2} \right. \text{ is a typical solution of } E^4 \Phi = 0 \text{ with } f(\mu) \text{ of the form} \\ \left. A P'_m(\mu) + B Q'_m(\mu) + A_1 P'_{m-2}(\mu) + B_1 Q'_{m-2}(\mu) \right\}$$

If $m=1$, it can be easily shown that the solutions so derived will correspond to those obtained already in equation 3·30* of reference 1.

In the particular case of solving the equation $(L_1 + L_2)^2 \phi = 0$ where the linear differential operators L_1 and L_2 are independent—in the sense that L_1 operates only on $f(\xi_1)$ and L_2 on $\psi(\xi_2)$ where $f(\xi_1)$ and $\psi(\xi_2)$ are arbitrary functions of the coordinates ξ_1 and ξ_2 . As an illustration, we may note Laplacian $\nabla^2_{x,\omega}$ in cylindrical coordinates, is of this form

$$\nabla^2_{(x,\omega)} \equiv L_1 + L_2; \quad L_1 \equiv \frac{\partial^2}{\partial x^2};$$

$$L_2 \equiv \frac{\partial^2}{\partial \omega^2} + \frac{1}{\omega} \frac{\partial}{\partial \omega};$$

To obtain particular solutions of $(L_1 + L_2)^2 \phi = 0$ i.e. $(L_1^2 + 2L_1L_2 + L_2^2) \phi = 0$, we assume ϕ to be of the form $X(\xi_1) Y(\xi_2)$ and dividing the equation by XY , one obtains $\frac{L_1^2(X)}{X} + 2 \frac{L_1(X)}{X} \cdot \frac{L_2(Y)}{Y} + \frac{L_2^2(Y)}{Y} = 0$. This suggests that the solution can be determined by solving for X and Y from

$$(18) \quad (L_1 \pm \lambda) X = 0 \text{ and } (L_2 \mp \lambda) Y = g(\xi_2) \text{ where } (L_2 \mp \lambda) g = 0$$

or

$$(18a) \quad (L_2 \pm \lambda) Y = 0 \text{ and } (L_1 \mp \lambda) X = f(\xi_1) \text{ where } (L_1 \mp \lambda) f = 0$$

where λ is a constant.

Illustrations:

$$L_1 = \frac{\partial^2}{\partial x^2}$$

$$L_2 = \frac{1}{\omega} \frac{\partial}{\partial r} \left(\omega \frac{\partial}{\partial r} \right) - 1/\omega^2$$

If $(L_1 \pm \lambda^2) f = 0$,

$$f(\xi_1) = a \frac{\cos}{\cosh} \lambda X + b \frac{\sin}{\sinh} \lambda X$$

according as the upper or lower sign is chosen. Hence any solution of $(L_1 \mp \lambda) X = f(\xi_1)$ can be expressed as

$$X \equiv \frac{\cos}{\cosh} \lambda x(a_1 + b_1 x) + \frac{\sin}{\sinh} \lambda x(c_1 + d_1 x).$$

If $\lambda = 0$, it can be easily proved that $X = a_1 + b_1 x + c_1 x^2 + d_1 x^3$.

Similarly, if $(L_2 \pm \lambda) Y = 0$,

$$Y = A_1 \frac{I_1}{J_1}(\lambda \omega) + B_1 \frac{K_1}{Y_1}(\lambda \omega) \text{ and } (A_1 \omega + B_1/\omega) (\lambda = 0)$$

*It may be pointed out here that the solutions r^{μ^2} , $r^{2\mu^2}$ are not "new" as given in reference 1, equation (3·30) but are implicitly stated through equations 3·19 and 3·8 of reference 1 for $n=1$. Also refer Appendix.

Hence the particular functions ωXY expressed as

$$I : \omega \left\{ A_1 \frac{I_1}{J_1}(\lambda\omega) + B_1 \frac{K_1}{Y_1}(\lambda\omega) \right\} \left\{ \frac{\cos}{\cosh} \lambda x (a_1 + b_1 x) + \frac{\sin}{\sinh} \lambda x (c_1 + d_1 x) \right\} \lambda \neq 0.$$

where $A_1, B_1, a_1, b_1, c_1, d_1$ and λ are arbitrary constants and

$$II : \omega (A_1 \omega + B_1/\omega) (a_1 + b_1 x + c_1 x^2 + d_1 x^3), \quad (\lambda = 0)$$

are solutions of $E^4 (\omega XY) = 0$.

Also, the solution of

$$(L_2 \pm \lambda) Y = \left\{ A_1 \frac{I_1}{J_1}(\lambda\omega) + B_1 \frac{K_1}{Y_1}(\lambda\omega) \right\} \quad \lambda \neq 0$$

can be proved to be

$$C_1 \frac{I_1}{J_1}(\lambda\omega) + D_1 \frac{K_1}{Y_1}(\lambda\omega) - \left[\frac{I_1}{J_1}(\lambda\omega) \int \omega \frac{K_1}{Y_1}(\lambda\omega) \left\{ A_1 \frac{I_1}{J_1}(\lambda\omega) + B_1 \frac{K_1}{Y_1}(\lambda\omega) \right\} d\omega \right. \\ \left. - \frac{K_1}{Y_1}(\lambda\omega) \int \omega \frac{I_1}{J_1}(\lambda\omega) \left\{ A_1 \frac{I_1}{J_1}(\lambda\omega) + B_1 \frac{K_1}{Y_1}(\lambda\omega) \right\} d\omega \right]$$

where A_1, B_1, C_1 and D_1 are constants. Hence some solutions of $E^4(\Phi) = 0$ are

$$\Phi = \omega XY = \omega \left\{ a_1 \frac{\cos}{\cosh} \lambda x + b_1 \frac{\sin}{\sinh} \lambda x \right\} \delta \left\{ C_1 \frac{I_1}{J_1}(\lambda\omega) + D_1 \frac{K_1}{Y_1}(\lambda\omega) \right\}$$

$$III: \quad - \frac{I_1}{J_1}(\lambda\omega) \int \omega \frac{K_1}{Y_1}(\lambda\omega) \left\{ A_1 \frac{I_1}{J_1}(\lambda\omega) + B_1 \frac{K_1}{Y_1}(\lambda\omega) \right\} d\omega \\ - \frac{K_1}{Y_1}(\lambda\omega) \int \omega \frac{I_1}{J_1}(\lambda\omega) \left\{ A_1 \frac{I_1}{J_1}(\lambda\omega) + B_1 \frac{K_1}{Y_1}(\lambda\omega) \right\} d\omega$$

For $\lambda = 0$, ωXY will be of the form,

$$IV: (a_1 + b_1 x) \omega \quad A_1 \omega + B_1/\omega + C_1 \omega \log \omega + C_2 \omega^3$$

The solutions I, II, III and IV have already been shown to be solutions of $E^4 \phi = 0$ in this paper, equations 7, 8, 9, 10 and elsewhere (reference 1, equations 2·9, 2·18, 2·26 2·31, 2·39 and 2·44)

In case the operator is of the form $f_1(\xi_1) f_2(\xi_2) (L_1 + L_2)$ where L_1 and L_2 are in terms of ξ_1 and ξ_2 coordinates only, let us assume a solution of the form $\frac{x(\xi_1)}{f_1(\xi_1)} \cdot \frac{y(\xi_2)}{f_2(\xi_2)}$ so that

$$f_1(\xi_1) f_2(\xi_2) \left[\frac{y}{f_2} L_1 \left(\frac{x}{f_1} \right) + \frac{x}{f_1} L_2 \left(\frac{y}{f_2} \right) \right] = f_1 y L_1 \left(\frac{x}{f_1} \right) + x f_2 L_2 \left(\frac{y}{f_2} \right) \\ f_1 f_2 (L_1 + L_2) \left\{ L_1 \left(\frac{x}{f_1} \right) + x f_2 L_2 \left(\frac{y}{f_2} \right) \right\} = f_1 f_2 \left\{ y L_1 \left[f_1 L_1 \left(\frac{x}{f_1} \right) \right] \right. \\ \left. + f_1 L_1 \left(\frac{x}{f_1} \right) L_2(y) + f_2 L_2 \left(\frac{y}{f_2} \right) L_1(x) + x L_2 \left(f_2 L_2 \left(\frac{y}{f_2} \right) \right) \right\}$$

and hence, representing the operator $f_1 f_2 (L_1 + L_2)$ by $f \delta^\xi$

$$\frac{f \delta^2 \xi \left\{ \frac{xy}{f_1 f_2} \right\}}{xy} = 0 \text{ implies}$$

$$(19) \quad \frac{L_1 \left[f_1 L_1 \left(\frac{x}{f_1} \right) \right]}{x} + \frac{L_1(x) L_2(y)}{x y} + \frac{L_2(y)}{y} \cdot \frac{f_1 L_1 \left(\frac{x}{f_1} \right)}{x} + \frac{L_2 [f_2 L_2 (y/f_2)]}{y} = 0$$

For the special case when $f_2(\xi_2) = 1$

$$(20) \quad \frac{L_1 \left\{ f_1 \left[L_1 \left(\frac{x}{f_1} \right) \right] \right\}}{x} + \frac{L_2(y)}{y} \left\{ \frac{L_1(x)}{x} + \frac{L_1(x/f_1)}{x/f_1} \right\} + \frac{L_2^2(y)}{y} = 0$$

It can be seen that the condition $\frac{L_2(y)}{y} = \lambda$ implies,

$$(21) \quad \frac{L_1 \left\{ f_1 \left[L_1 \left(\frac{x}{f_1} \right) \right] \right\}}{x} + \lambda \left\{ \frac{L_1(x)}{x} + \frac{L_1(x/f_1)}{x/f_1} \right\} + \lambda^2 = 0$$

from which an expression for X can be derived. If $\frac{L_1(x)}{x} = \alpha_1$ and also $\frac{L_1(x/f_1)}{x/f_1} = \alpha_2$

(i.e. if both X and X/f_1 are eigen functions of the operator L_1), we find that

$$\alpha_1 \alpha_2 + \frac{L_2(y)}{y} \left\{ \alpha_1 + \alpha_2 \right\} + \frac{L_2^2(y)}{y} = 0$$

$$(22) \text{ or } (L_2 + \alpha_1)(L_2 + \alpha_2)y = 0$$

where α_1, α_2 are constants. This equation can be solved easily for Y thereafter, and the complete solution thus obtained.

ILLUSTRATION

Spherical coordinates:

$$L_1 \equiv \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) ; f_1 = 1/r^2$$

$$\equiv \theta(\theta + 1) ; \theta = \frac{\partial}{\partial z} \text{ where } z = \log r.$$

For the operator L_1 , r^n will be an eigen function with the eigen value $(n^2 + n)$ so that r^{n-2} will be an eigen function with the eigen value $(n^2 - 3n + 2)$.

$$\text{i.e. } \frac{L_1(r^n)}{r^n} = n(n+1) \text{ and } \frac{L_1(r^n/r^2)}{r^{n-2}} = n^2 - 3n + 2;$$

correspondingly, one can solve (for Y) the equation

$$[L_2 + n(n+1)][L_2 + (n-2)(n-1)]y = 0$$

Some of the solutions can be,

$$Y = A_1 P'_n(\mu) + B_1 Q'_n(\mu) \text{ and}$$

$$A_1 P'_{n-2}(\mu) + B_1 Q'_{n-2}.$$

In particular, for $n = 2$

$$Y = A_1 P_2'(\mu) + B_1 Q_2'(\mu) \text{ and}$$

$$(A_1' + B_1'\mu)/\sqrt{1-\mu^2} \text{ or } A_1\mu\sqrt{1-\mu^2} \text{ and } (A_1' + B_1'\mu)/\sqrt{1-\mu^2},$$

confining to the Legendre function of the first kind. A solution can therefore be written as $A_1\mu\sqrt{1-\mu^2}$ or $(A_1' + B_1'\mu)/\sqrt{1-\mu^2}$. Consequently, the solutions for $E^4\phi = 0$ can, hence be expressed as $rA_1\mu(1-\mu^2)$ and $r(A_1' + B_1'\mu)$

A_1, A_1' and B_1' : arbitrary constants).

Similarly one can derive the solutions corresponding to other powers.

Discussions of a similar nature can be extended to some other operators as well.

Defining $E_\nu^2 \equiv \frac{\partial^2}{\partial \omega^2} - \frac{\nu}{\omega} \frac{\partial}{\partial \omega} + \frac{\partial^2}{\partial x^2}$, it can be proved easily that

$$(23) E_\nu^2 \left(\frac{\nu+1}{\omega^2} F \right) = \omega^{\frac{\nu+1}{2}} \left\{ \frac{\partial^2}{\partial \omega^2} + \frac{1}{\omega} \frac{\partial}{\partial \omega} - \frac{(\nu+1)^2}{4\omega^2} + \frac{\partial^2}{\partial x^2} \right\}$$

which corresponds to the operation of the three dimensional Laplacian ∇^2 on a function

which varies with ϕ as $e^{i \left(\frac{\nu+1}{2} \phi \right)}$

For $\nu = 1$, $E_\nu^2 \Rightarrow E^2$ discussed in the paper, and $\frac{\nu+1}{2} = 1$; Hence,

$$(24) E_\nu^2 \left(\frac{\nu+1}{\omega^2} F(\omega, x) e^{i \frac{\nu+1}{2} \phi} \right) = \omega^{\frac{\nu+1}{2}} \nabla^2 \left(F e^{i \frac{\nu+1}{2} \phi} \right)$$

$$(24)a E_\nu^4 \left[\frac{\nu+1}{\omega^2} F(\omega, x) e^{i \frac{\nu+1}{2} \phi} \right] = \omega^{\frac{\nu+1}{2}} \nabla^4 \left(F e^{i \frac{\nu+1}{2} \phi} \right)$$

and hence corresponding to a solution of $\nabla^4 \left(F e^{i \frac{\nu+1}{2} \phi} \right) = 0$ with F independent

of ϕ , a solution of $E_\nu^4 f = 0$ exists such that $f = \omega F^{\frac{\nu+1}{2}}$. An operator of the form

$H_\nu \equiv \left(\frac{\partial^2}{\partial \omega^2} - \frac{\nu}{\omega} \frac{\partial}{\partial \omega} + \frac{\partial^2}{\partial x^2} - \kappa^2 \right)$ will correspond to the Hamiltonian

$$(25) (\nabla^2 - \kappa^2) \text{ since } H_\nu \left(\frac{\nu+1}{\omega^2} F \right) = \omega^{\frac{\nu+1}{2}} (\nabla^2 - \kappa^2) \left(F e^{i \frac{\nu+1}{2} \phi} \right)$$

with F independent of ϕ .

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REFERENCE

APPENDIX

To solve

$$A(1) \left(1 - \mu^2\right) \frac{d^2}{d\mu^2} \left\{ \left(1 - \mu^2\right) \mu^n \right\} + 2\alpha \left(1 - \mu^2\right) \mu^n + (\alpha - 3)(\alpha - 1) \mu = 0$$

(cf: equation 3.22, Reference 1)

Denote by θ_1 and θ_2 the operators $\left(1 - \mu^2\right) \frac{d^2}{d\mu^2}$ and

$$\left\{ \left(1 - \mu^2\right) \frac{d^2}{d\mu^2} - 2\mu \frac{d}{d\mu} - \frac{1}{1 - \mu^2} \right\}$$

respectively; By simple calculations, it may be shown that

$$\theta_1 \{N(\mu) \sqrt{1 - \mu^2}\} = \sqrt{1 - \mu^2} \cdot \theta_2 \{N(\mu)\}$$

so that

$$\theta_1^2 N(\mu) \sqrt{1 - \mu^2} = \theta_1 [\sqrt{1 - \mu^2} \cdot \theta_2^2 N(\mu)] = \sqrt{1 - \mu^2} \cdot \theta_2^2 N(\mu)$$

Equation A(1) can be transformed into the form

$$A(2) \quad \theta_1^2 \mu + 2\alpha \theta_1 \mu + (\alpha - 3)(\alpha - 1) \mu = 0.$$

$N\sqrt{1 - \mu^2}$ is a solution of A(2), provided N satisfies the equation,

$$A(3) \quad [\theta_2^2 + 2\alpha\theta_2 + (\alpha - 3)(\alpha - 1)] N = 0.$$

Denoting the roots $(-\alpha \pm \sqrt{4\alpha - 3})$ of the equation $x^2 + 2\alpha x + (\alpha - 3)(\alpha - 1) = 0$ by α_1 and α_2 respectively, we find that

$$N = A_1 P_{n-1}^1(\mu) + B_1 Q'_{n-1}(\mu) \\ + A_2 P_{n-3}^1(\mu) + B_2 Q'_{n-3}(\mu)$$

where $3 + n(n - 3)$ has been written for α .

The solution of $(D^2 - 3D + 3)R = \alpha R$

(cf: equation 3.20, reference 1)

can be expressed as $R = C_1 r^n + C_2 r^{-(n-3)}$.

(note: $\alpha = 3 + n(n - 3)$). Hence, a solution of $E^4 \Phi = 0$ will be,

$$[C_1 r^n + C_2 r^{-(n-3)}] [A_1 P'_{n-1}(\mu) + B_1 Q'_{n-1}(\mu) + A_2 P'_{n-3}(\mu) + B_2 Q'_{n-3}(\mu)] \\ (\sqrt{1 - \mu^2})$$

(A_1, B_1, C_1, A_2, B_2 , and C_2 are arbitrary constants).

This result has been implicitly stated through equation (17) of this paper.

In particular, for $n = 1, \alpha = 1$ and the solutions given by equation 3.30 of reference (1) can be deduced.