

# SOME NEW COORDINATE SYSTEMS IN A RIEMANNIAN SPACE

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This paper defines two new coordinate systems viz. pseudo-geodesic and pseudo-Riemannian. Spaces for which the equations of pseudo-geodesics admit a first integral have also been studied.

Consider a space  $V_n$  of coordinates  $x^i$  ( $i=1, \dots, n$ ) and metric  $g_{ij} dx^i dx^j$ , immersed in a Riemannian  $V_m$  of coordinates  $y^\alpha$  ( $\alpha=1, \dots, m$ ) and metric  $a_{\alpha\beta} dy^\alpha dy^\beta$ . Considering a congruence of curves  $\lambda_{\tau 1}^\alpha$  given by

$$\lambda_{\tau 1}^\alpha = t_{\tau 1}^i y_{i1}^\alpha + \sum_{\nu} C_{\nu\tau 1} N_{\nu 1}^\alpha, \quad (1)$$

Pan<sup>1</sup> defined the relative first curvature vector of the curve  $C$  of the subspace  $V_n$  as follows:

$$\eta^i = p^i - \sum_{\nu, \tau} \bar{C}_{\nu\tau 1} K_{\nu 1} t_{\tau 1}^i + \sum_{\nu, \tau} \bar{C}_{\nu\tau 1} K_{\nu 1} t_{\tau 1k} \frac{dx^k}{ds} \frac{dx^i}{ds} \quad (2)$$

He also defined pseudo-geodesic curves of the subspace as the curves for which relative first curvature vanishes at each and every point of the curve. Pan<sup>1</sup> obtained the differential equation of pseudo-geodesics in the following form :

$$\frac{d^2 x^i}{ds^2} + U_{jk}^i \frac{dx^j}{ds} \frac{dx^k}{ds} = 0 \quad (3)$$

where

$$U_{jk}^i = \left\{ \begin{matrix} i \\ jk \end{matrix} \right\} - \sum_{\nu, \tau} \bar{C}_{\nu\tau 1} \Omega_{\nu 1jk} \left( t_{\tau 1}^i - t_{\tau 1l} \frac{dx^l}{ds} \frac{dx^i}{ds} \right). \quad (4)$$

Using this relative connection  $U_{jk}^i$ , Upadhyay & Trivedi<sup>2</sup> defined the relative covariant derivative of a mixed tensor  $X_j^i$  as follows:

$$X_{j;k}^i \stackrel{\text{def}}{=} \partial_k X_j^i + X_j^l U_{lk}^i - X_l^i U_{jk}^l.$$

## PSEUDO-GEODESIC COORDINATES

If  $s$  is the arc length of a curve  $C$  through a point  $P_0$ , measured from that point, then we have

$$x^i = x_0^i + \left( \frac{dx^i}{ds} \right)_0 s + \frac{1}{2} \left( \frac{d^2 x^i}{ds^2} \right)_0 s^2 + \dots \quad (5)$$

the subscript zero denoting that the function is to be evaluated at the point  $P_0$ . If  $C$  is a pseudo-geodesic, the coefficient of  $\frac{1}{2}s^2$  is equal to  $-U_{jk}^i \xi^j \xi^k$ , where

$$\xi^j = \left( \frac{dx^j}{ds} \right)_0. \quad (6)$$

Consequently in case of a pseudo-geodesic we have

$$x^i = x_0^i + \xi^i s - \frac{1}{2} U_{jk}^i \xi^j \xi^k s^2 + \dots \quad (7)$$

We shall now define a system of coordinates for which

$$U_{jk}^i = 0, \quad (8)$$

and we call such a system of coordinates as the pseudo-geodesic coordinate system with pole at  $P_0$ .

From the definition of relative covariant derivative it is clear that :

'At the pole of a pseudo-geodesic coordinate system the components of relative covariant derivative are ordinary derivatives'.

The condition that a system of coordinates be pseudo-geodesic, with pole at  $P_0$ , may be expressed in another form as follows :

If in the relation

$$U_{ij}^h \frac{\delta x^d}{\delta \tilde{x}^k} = U_{ab}^d \frac{\delta x^a}{\delta \tilde{x}^i} \frac{\delta x^b}{\delta \tilde{x}^j} + \frac{\delta^2 x^d}{\delta \tilde{x}^i \delta \tilde{x}^j} \quad (9)$$

we interchange the  $x$ 's and the  $\tilde{x}$ 's, we may write the relation (8) in the form

$$-U_{ab}^d \frac{\partial \tilde{x}^a}{\partial x^i} \frac{\partial \tilde{x}^b}{\partial x^j} = \frac{\partial^2 \tilde{x}^d}{\partial x^i \partial x^j} - U_{ij}^h \frac{\partial \tilde{x}^d}{\partial x^h} = \left( \frac{\partial \tilde{x}^d}{\partial x^i} \right)_{;j} \quad (10)$$

If the  $\tilde{x}$ 's are pseudo-geodesic coordinates with pole at  $P_0$ , the coefficients  $\bar{U}_{ab}^d$  all vanish at this point and therefore also the function  $(\partial \tilde{x}^d / \partial x^i)_{;j}$ . Conversely if  $(\partial \tilde{x}^d / \partial x^i)_{;j}$  all vanish at  $P_0$ , it follows from (9), (since the functional determinant  $\partial \tilde{x} / \partial x$  is not zero) that the relative connection  $\bar{\Gamma}_{ab}^d$  all vanish at  $P_0$ , showing that the  $x$ 's are pseudo-geodesic coordinates. Thus :

*Theorem I*

'The necessary and sufficient condition that a system of coordinates be pseudo-geodesic with pole at  $P_0$  is that  $(\partial \tilde{x}^d / \partial x^i)_{;j} = 0$ '.

Now we shall prove the existence of a pseudo geodesic coordinate system for any  $V_n$  with an arbitrary pole at  $P_0$ .

Let  $x^j$  be a general system of coordinates whose values at  $P_0$  are  $x_0^j$  and  $\tilde{x}^i$  another system of coordinates defined by

$$\tilde{x}^i = a_k^i (x^k - x_0^k) + \frac{1}{2} a_h^i U_{jk}^h (x^j - x_0^j) (x^k - x_0^k), \quad (11)$$

where the coefficients  $a_k^i$  are constants and the determinant  $|a_k^i|$  is not zero. Then at the point  $P_0$  we have

$$(\partial \tilde{x}^i / \partial x^k)_0 = a_k^i \quad (12)$$

and

$$(\partial^2 \tilde{x}^i / \partial x^j \partial x^k)_0 = a_h^i U_{jk}^h \quad (13)$$

Consequently, at  $P_0$  the right hand side of (9) takes the form

$$a_h^i U_{jk}^h - a_h^i U_{0jk}^h = 0,$$

and the conditions are therefore satisfied that the coordinates  $\tilde{x}^i$  be pseudo-geodesics with pole at  $P_0$ .

Now it is easy to prove that for an arbitrary curve  $C$  in  $V_n$  it is possible to choose coordinates which are pseudo-geodesics at every point of  $C$ .

Since we know that for a geodesic coordinate system with pole at  $P_0$  we have

$$\left\{ \begin{matrix} i \\ jk \end{matrix} \right\}_0 = 0, \quad (14)$$

therefore from (4) we have the following :

*Theorem II.*

'The necessary and sufficient condition for geodesic coordinates to become pseudo-geodesic coordinates is given by either of the following :

- (i) the congruence be normal,
- (ii) the curve be an asymptotic line'.

PSEUDO-RIEMANNIAN COORDINATES

Let  $C$  be any pseudo geodesic through a given point  $P_0$  and  $s$  be its arc length measured from  $P_0$ . To each point  $P$  of the pseudo-geodesic we assign coordinates  $y^i$  such that

$$y^i = \xi^i s. \tag{15}$$

The quantities  $\xi^i$  determine the particular pseudo-geodesic through  $P_0$  ; and the value of  $s$  then determines the point  $P$  on this pseudo-geodesic. As there is a pseudo-geodesic from  $P_0$  to any point of  $V_n$ , each point of the space has definite coordinates  $y^i$  assigned to it. These are the pseudo-Riemannian coordinates referred to. We shall now show that these are particular type of pseudo-geodesic coordinates with pole at  $P_0$ .

If  $\bar{U}_{jk}^i$  are the coefficients of relative connections calculated with respect to the  $y$ 's, the differential equations of the pseudo-geodesics of  $V_n$  in terms of these coordinates are

$$\frac{d^2 y^i}{ds^2} + \bar{U}_{jk}^i \frac{dy^j}{ds} \frac{dy^k}{ds} = 0. \tag{16}$$

By virtue of (14) and (15) we can easily obtain

$$\bar{U}_{jk}^i \xi^j \xi^k = 0 \tag{17}$$

and therefore

$$\bar{U}_{jk}^i y^j y^k = 0 \tag{18}$$

holds throughout the space.

Conversely if (17) are satisfied then (15) are satisfied by (14) and the  $y$ 's are pseudo-Riemannian coordinates. Thus we have the following :

*Theorem III*

'If  $U_{jk}^i$  are the relative connection for a coordinate system  $y$  a necessary and sufficient condition that these be pseudo-Riemannian coordinates is that the equations'

$$U_{jk}^i y^j y^k = 0 \tag{19}$$

hold throughout the space.

The equations (16) hold at  $P_0$  for all pseudo-geodesics through that point, that is to say, for all directions  $\xi^i$ . Consequently the coefficients  $\bar{U}_{jk}^i$  must vanish at that point, showing that the pseudo-Riemannian coordinates are pseudo-geodesic coordinates with pole at  $P_0$ .

By using the definitions of Riemannian and pseudo-Riemannian coordinates we easily obtain the following :

*Theorem IV*

'The necessary and sufficient condition for the Riemannian coordinates to become pseudo-Riemannian coordinates is given by either of the following :

- (i) the congruence be normal,
- (ii) the curve be an asymptotic line.

PSEUDO-GEODESICS OF A SPACE

If each integral of the equations (3) of the pseudo-geodesics of a space satisfies the condition

$$a_{i_1 \dots i_r} \frac{dx^{i_1}}{ds} \dots \frac{dx^{i_r}}{ds} = \text{Constant}, \tag{20}$$

the equations (3) are said to admit a first integral of  $r$ th order.

Now let us suppose that the tensor  $a_{i_1 \dots i_r}$  is symmetric in all the subscripts, then differentiating (19) relative covariantly with respect to  $x^j$  and multiplying by  $dx^j/ds$  and making use of

$$(dx^j/ds) (dx^i/ds) : j = 0 \tag{21}$$

we obtain

$$a_{i_1 \dots i_r} : j \frac{dx^{i_1}}{ds} \dots \frac{dx^{i_r}}{ds} \frac{dx^j}{ds} = 0 \tag{22}$$

Since the equations (21) must be satisfied identically, we must have

$$P(a_{i_1 \dots i_r} : j) = 0 \tag{23}$$

where  $P$  indicates the sum of the  $(m+1)$  terms obtained by permuting the subscripts cyclically.

In particular, if (19) is of the first order, i.e., if

$$a_i (dx^i/ds) = \text{Constant}, \tag{24}$$

the condition (22) reduces to

$$a_{i:j} + a_{j:i} = 0, \tag{25}$$

i.e., the vector  $a_i$  is a relative Killing vector<sup>2</sup>. Thus we have:

**Theorem V**

'If the equation of a pseudo-geodesic admits an integral of the first order then the covariant vector  $a_i$  is a relative Killing vector.'

REFERENCES

1. PAN, T. K., Relative first curvature and relative parallelism in a subspace of a Riemannian space, *Univ. Nac. Tucuman Rev.*, A 11 (1967), 3-9.
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