

# Optimal Decision Procedure to Declare Human Fatigue and Prediction of 3-Mean Repair Times with One Repairman

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## ABSTRACT

This paper gives an optimum procedure to decide whether fatigue is present in a repairman and if it is true prediction of the 3-mean repair times of the three failed systems.

**Keywords:** Mean repair times, optimal decision procedure, human fatigue

## NOMENCLATURE

MRT	Mean repair time
A, B, C	Three support systems for which MRTs are needed.
$\eta_1, \eta_2$	Multiplying constant for $t_3$
$\alpha$	Type I error
$\beta$	Power function
$t_1, t_2, t_3$	3-MRTs of support systems A, B, C, respectively
$Z_b$	A random variable which takes values between 1 or 0, depending on whether fatigue of repairman exists or not.
$S$	$S = \sum_1^M Z_b$
$M$	Total number of MRTs for which repair completions are over, i.e., $M = 3$
$H_0$	Null hypothesis
$H_1$	Alternate hypothesis

## 1. INTRODUCTION

Consider a multisystem model ( $N + 3$ ), where  $N$  is the number of systems, in the major system which has three additional systems called support systems. These support systems are denoted by A, B and C. The repair of A, B and C is taken by a single repairman in the order A, B, C. The mean repair completion times for the three support systems A, B and C (3-MRTs) are denoted by symbols  $t_1, t_2$  and  $t_3$ . The human fatigue problems enter the 3-MRT process since there is one repairman only. In such cases, it is easy to think and formulate the whole problem as problems in the decision-making<sup>1</sup> and decision procedures.

## 2. DECISION-MAKING PROBLEM

The decision-making problem is formulated as

$H_0$	No fatigue exists in the repairman
$H_1$	Fatigue exists in the repairman, or in other words $t_1 < t_2 < t_3$

## 2.1 Decision Procedure

- Step 0 Choose  $\alpha$  (type I error)
- Step 1 If  $t_1 < t_2 < t_3$ , then  $Z_b = 1$ , otherwise  $Z_b = 0$
- Step 2 Compute  $S = \sum_{b=1}^M Z_b$
- Step 3 Put  $M = 1, 2, 3$  in summation  $S$  successively
- Step 4 Determine  $k$ , such that  $\text{binf}(k; 1/6, 3) = \alpha$
- Step 5 Reject  $H_0$  iff  $S = 2$  and if  $S \neq 1$ .

## 2.2 Analysis

$$\text{Define } h(t_1) = \int_{t_1}^{\infty} dt_2 \int_{t_2}^{\infty} dt_3 \exp f(t) \exp f(t) \quad (1)$$

It is to be remembered that Eqn (1) is true regardless of  $H_0$  and  $H_1$ .

It can be easily shown that

$$\begin{aligned} P_0 &= \Pr \{ Z_b = 1; \text{ regardless of } H_0, H_1 \} \\ &= E \{ h(t_1) \} \end{aligned} \quad (2)$$

where  $E$  is the expected value.

Now

$$\Pr \{ S = r; H_0 \text{ is true} \} = \text{binom}(r; 1/6, 3) \quad (3)$$

$$\Pr \{ S = r; H_1 \text{ is true} \} = \text{binom}(r; P_1, 3) \quad (4)$$

It can easily be proved that  $P_1 < 1/6$  under  $H_1$ .

Hence, from Neyman-Pearson lemma, decision procedure [Eqns (1) to (4)] is optimum. The performance of decision rule [Eqn (3)] is evaluated for two illustrations. The power function is:

$$\beta = \text{binf}(3; P_1; 3) \quad (5)$$

The Eqn (5) can be illustrated for two cases by putting the expression for

$$F(t_1) = F(t_3 - 2\Delta)$$

$$F(t_2) = F(t_3 + \Delta)$$

$$F(t_3) = \exp f(t)$$

The second illustration can be given for

$$F(t_1) = F(\eta_1 t_3), \eta_1 < 1$$

$$F(t_2) = F(\eta_2 t_3), \eta_2 < 1$$

$$F(t_3) = \exp f(t)$$

## 3. CONCLUSION

Two problems have been analysed. The first problem is a decision procedure to decide whether human fatigue is present in the repairman, when  $M = 3$ . By setting probabilities  $P_0, P_1$  and  $P_2$  equal to  $t_1, t_2$  and  $t_3$  (3-MTRs) after deciding that there is human fatigue in the repairman.

Type I error and  $M$  as  $\alpha = 0.05$  and  $M = 3$ , respectively can be chosen. The value of  $k$  in the relation  $S \leq k$  should be chosen as one among any values for  $k = 2$  or  $k = 3$ .

## REFERENCES

1. Srinivasan, V.S. Application of discrete Fourier transform to decision-making in reliability. *IEEE Trans. Reliab.*, 1978, **R-27**(5), 372.